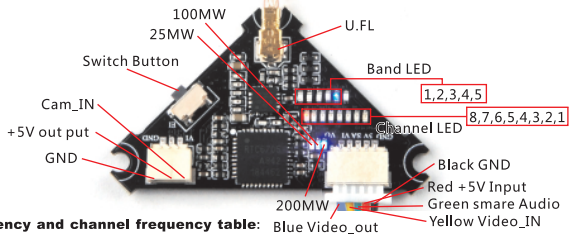


Specifications

Brand Name: Eachine
Item Name: 2S 75mm Brushless Whoop racer drone BNF
Wheelbase: 75mm
Size: 98mm*98mm*36mm
Weight: 33g(without battery)

VTX Bands and Channels setup

Blue LEDs and Red LED8 light on, indicating frequency
5917MHZ(BAND5 and CH8)
Blue LED1 and Red LED2 light on, indicating frequency
5845MHZ(BAND1 and CH2)



Frequency and channel frequency table:

FR	CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Band1(A)		5865M	5845M	5825M	5805M	5785M	5765M	5745M	5725M
Band2(B)		5733M	5752M	5771M	5790M	5809M	5828M	5847M	5866M
Band3(E)		5705M	5685M	5665M	5665M	5885M	5905M	5905M	5905M
Band4(F)		5740M	5760M	5780M	5800M	5820M	5840M	5860M	5880M
Band5(R)		5658M	5695M	5732M	5769M	5806M	5843M	5880M	5917M

There are 3 ways to switch the vtx channels:

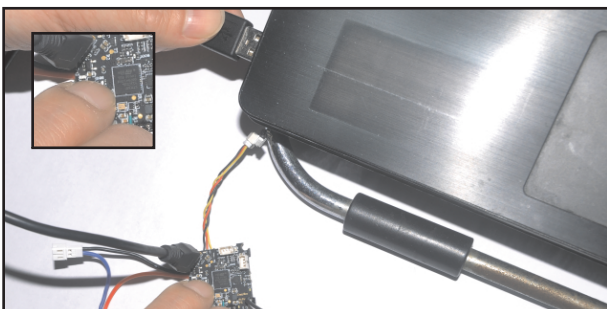
- Long press the switch button to change the Band of the VTX, shorter press the switch button to change the channels of the VTX.
(Can't save, it will lost the channel while re-power for the Trashcan since the Smartaudio function enabled)
- Go to Betaflight CLI, type the command:
Set vtx_band=3
Set vtx_channel=1
Set vtx_freq=5705
save
Notes: The vtx_freq should match the vtx_band and vtx_channel as the VTX Channel list shows.
For example, if you set vtx_freq=5732, you should set vtx_band=5 and vtx_channel=3
- Enable Smartaudio for UART1, then move the stick of the transmitter (THR MID+YAW LEFT + PITCH UP) to enter OSD Menu, Enter to VTX SA to set VTX Band and channel

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200	Off	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	115200	Off	Disabled AUTO	Disabled AUTO	TBS SmartAud AUTO
UART2	115200	Off	Disabled AUTO	Disabled AUTO	Disabled AUTO



Binding procedure

1. Press and hold the bind button and then Plug the USB to power for the Crazybee F4 PRO FS flight controller, the LED Combo(2 red LED on 2 white LED) will blinking fast, this indicates the Crazybee F4 PRO FS flight controller is in binding mode and then release the binding button



Another easy way to getting into binding mode(Need the latest Firmware):
Plug usb and go to the CLI command in the Betaflight configurator, then type "bind_rx_spi", the Crazybee F4FS Pro flight controller will get into binding mode, and then you just make the Flysky transmitter to Binding with it.

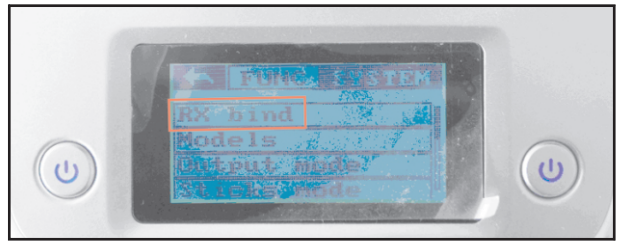
```

$M>-lUvY71-+SM>yt ARM; ANGLE; HORIZON; HEADFREE; FAILSAFE; ANTI C
MIX; CAMERA CONTROL 1; CAMERA CONTROL 2; CAMERA CONTROL 3; FLIP O
CONTROL; -SM>- , 0001 070000+0 1000 070-
Entering CLI Mode, type 'exit' to return, or 'help'

# bind_rx_spi
Binding ..
    
```

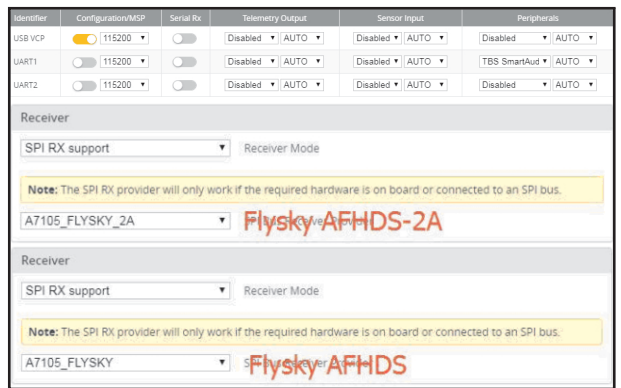
Trashcan 2S brushless whoop Racing Drone Flysky version

- Turn on your Flysky transmitter, and Choose receiver mode AFHDS-2A or AFHDS according to your Betaflight receiver configuration(A7105_Flysky_2A=AFHDS-2A, A7105_Flysky=AFHDS)
- ENT RX [BIND] to binding with the Crazybee F4 POR Flight controller, the LED Combo(2 red LED and 2 white LED) will getting to be solid on the flight controller, this indicate binding successfully, the AFHDS-2A radio will auto exist the binding mode but the AFHDS radio should exist binding mode by yourself.



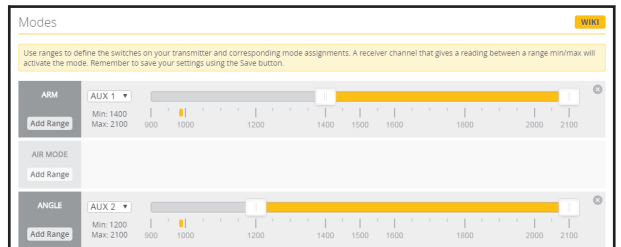
Receiver configuration

Please set Receiver mode to be SPI RX Support from the Configuration tab of the Betaflight Configurator, then select A7105_Flysky_2A Provider for AFHDS-2A Protocol Radio transmitter or Select A7105_Flysky Provider for AFHDS Protocol Radio transmitter, don't enable Serial RX since the Crazybee F4 PRO Flight controller is integrated SPI BUS Receiver



Arm/Disarm the Motor

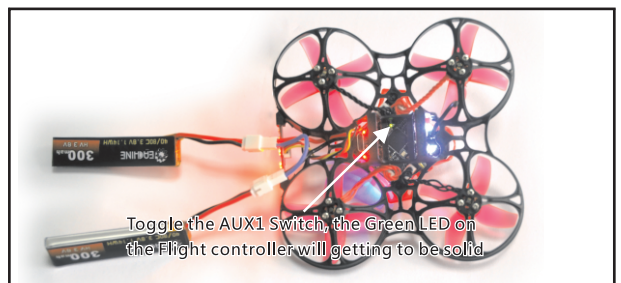
1. The Default Arm/Disarm switch for Trashcan is AUX1(Channel 5),and you can also customize it with Betaflight Configurator.



2. Set Arm/Disarm switch for your Flysky Radio: Move to the Aux.channels interface, Set "SWA" or "SWB" or "SWC" switch etc. for Ch5 to ARM/DISARM the motor.

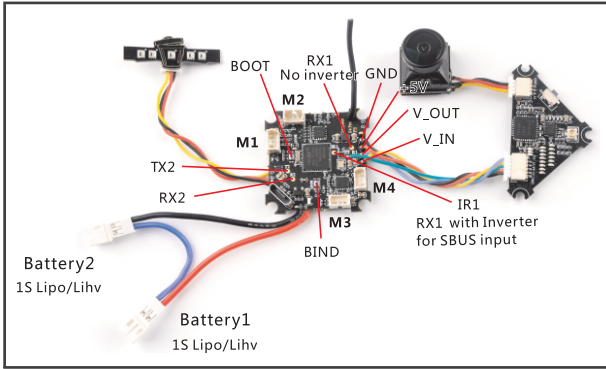
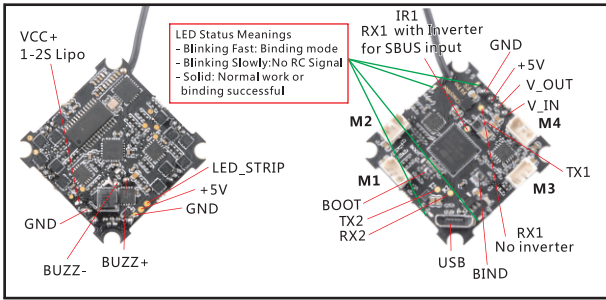


3. The default channel map for Trashcan Flysky version is AETR1234, please make sure your transmitter is matched, otherwise it will can't be armed. Toggle the AUX1 Switch, the Green LED on the flight controller will getting to be solid, this indicates the motor was armed. And also you can found "Armed" displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Trashcan level before arming. Be careful and enjoy your flight now!

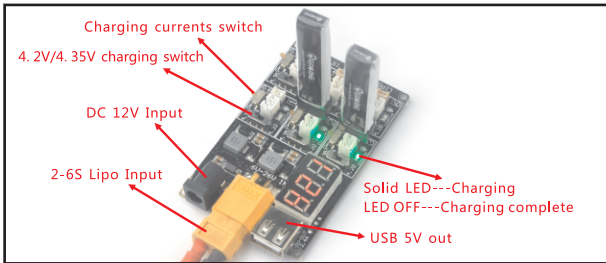
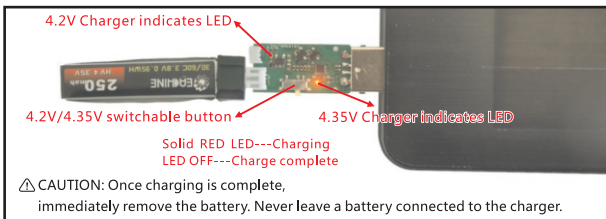


Toggle the AUX1 Switch, the Green LED on the Flight controller will getting to be solid

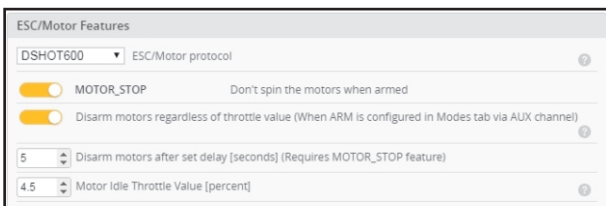
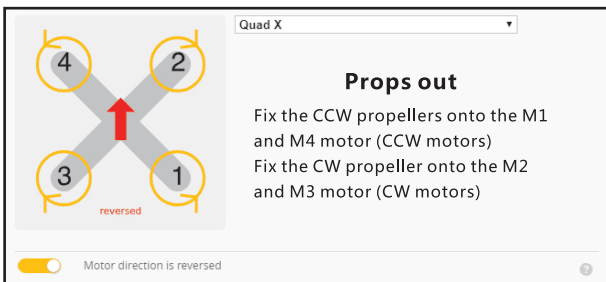
Flight controller connection diagram



Charger the Lipo Battery



Mixer type and ESC/motor protocol



Default PID setting

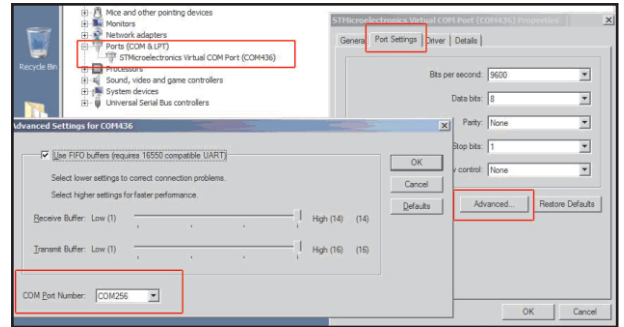
	Proportional	Integral	Derivative	Feedforward	RC Rate	Super Rate	Max Vel [deg/s]	RC Expo
Basic/Acro								
ROLL	46	45	25	60	1.20	0.75	960	0.00
PITCH	50	50	27	60	1.20	0.75	960	0.00
YAW	45	100	0	100	1.30	0.80	1300	0.00

ESC Check and Flash firmware

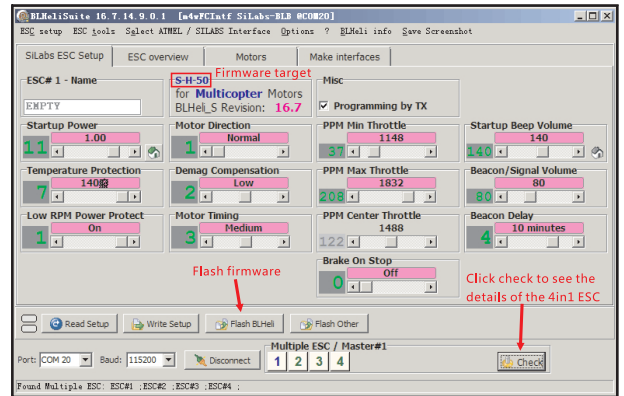
1. Download New release BLHeliSuite from: <https://www.mediafire.com/folder/dx6kfaasyo241/BLHeliSuite>
2. Connect the Crazybee F4 PRO Flight controller to computer and power for it with battery



3. Open the Device Manager of your computer, find the Ports, please make sure the Com port Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the following step:

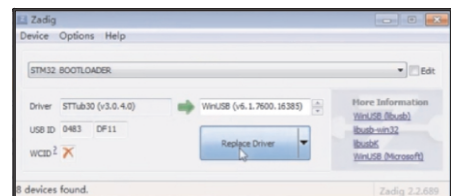


4. Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli_s firmware via the BLHELISUITE, the firmware Target is "S-H-50"



Flight controller firmware update

1. Install latest STM32 Virtual COM Port Driver <http://www.st.com/web/en/catalog/tools/PE257938>
2. Install STM BOOTLOAD Driver (STM Device in DFU MODE)
3. Open Betaflight configurator and choose firmware target "CrazybeeF4F5", then select the firmware version.
4. There are 2 ways to get in DFU Mode: 1). solder the boot pad and then plug USB to computer 2). loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically.
5. Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver.
6. Reconnect the flight controller to the computer after replace driver done, and open Betaflight Configurator, loading firmware and flash.



*We will update the firmware for Crazybee F4 PRO and release to our website in time.

"Flip over after crash" procedure

Set one channel of your radio transmitter to activate the Flip over function in the Mode tab of Betaflight configurator.

